DRIES CARDINAELS

Ph.D. Researcher \sim Freelancer



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SUMMARY

Exploring immersive VR technologies for intuitive and precise control in telerobotics, enhancing usability and accessibility in human-robot interaction. Our research focuses on innovative VR interaction methods, aiming to simplify complex tasks and expand telerobotic applications across industries.

EDUCATION —	
9/2021 - 7/2023	Master's Degree in Computer Science (Magna Cum Laude)Hasselt UniversityThesis: Studying and Analyzing Implementations and Techniques in a Telerobotic EnvironmentProf. Dr. Kris Luyten & Prof. Dr. Frank van Reeth
9/2018 - 7/2021	Bachelor's Degree in Computer Science (Cum Laude)Hasselt UniversityThesis: Serious Game to Educate Heart PatientsProf. Dr. Gustavo Rovelo Ruiz
RESEARCH EXPE	RIENCE
11/2023 - Present	Ph.D. Human-Robot InteractionHasselt UniversityThesis: Augmenting Human Capabilities to Perform Complex Tasks Through Telerobotics(Advisor) Prof. Dr. Kris Luyten & (Co-Advisor) Prof. Dr. Raf Ramakers
9/2023 - 11/2023	ResearcherHasselt UniversityExpertise Centre for Digital Media, Diepenbeek, Belgium
TEACHING EXPE	
2/2024 - Present	Project Software Ontwikkeling en Professionele Vaardigheden 2252
2/2024 - Present	Tools and Technologies for Interactive System Development 2184
9/2023 - 1/2024	Computer Architecture 4863
9/2023 - 1/2024	Object Oriented Programming II 4183
9/2023 - 1/2024	Computational Fabrication 4169/4719
THESIS ADVISING	3
2/2024 - Present	Bachelor Thesis on Collaborative Robots Computer Science We explore the use of collaborative robots, acting as extra 'hands' to assist in tasks requiring precision, such as soldering or detailed modeling
2/2024 - Present	Bachelor Thesis on Precise Delta Robot ManufacturingIndustrial EngineeringDeveloping a prismatic delta robot focused on the precise synchronization of three linear actuators, aiming for significant accuracy improvements for industrial applications
PUBLICATIONS	
March 2024	D. Cardinaels , B. van Deurzen, R. Ramakers, & K. Luyten, AntHand: Interaction techniques for precise telerobotic control using scaled objects in virtual environments, in Human-Robot Interaction 2024, Late Breaking Reports
March 2024	B. van Deurzen, D. Cardinaels , G. Rovelo Ruiz, & K. Luyten, A VR prototype for one-dimensional move- ment visualizations for robotic arms, in The 7th International Workshop on Virtual, Augmented, and Mixed- Reality for Human-Robot Interactions
PRESENTATIONS	;
March 2024	Poster Presentation HRI '24 ACM/IEEE International Conference on Human-Robot Interaction, Boulder (CO), USA
LANGUAGES —	Dutch - Native, English - B2, Italian - A1